

$$\begin{bmatrix} n \underline{A_{11}} & \underline{A_{12}} \\ \underline{A_{21}} & \underline{D} \end{bmatrix} \times \begin{bmatrix} \underline{\Delta Q} \\ \underline{\Delta H} \end{bmatrix} = \begin{bmatrix} \underline{-dE} \\ \underline{-dG} \end{bmatrix}$$

For our example (assume D-W):

$$\begin{bmatrix} 2K_1/Q_1 & 0 & 0 & 0 & 0 & 0 & 0 & +1 & 0 & 0 & 0 & 0 \\ 0 & 2K_2/Q_2 & 0 & 0 & 0 & 0 & 0 & 0 & +1 & 0 & 0 & 0 \\ 0 & 0 & 2K_3/Q_3 & 0 & 0 & 0 & 0 & +1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2K_4/Q_4 & 0 & 0 & 0 & 0 & -1 & +1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2K_5/Q_5 & 0 & 0 & 0 & 0 & -1 & +1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2K_6/Q_6 & 0 & 0 & 0 & 0 & -1 & +1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2K_7/Q_7 & -1 & 0 & 0 & +1 & 0 \\ \hline +1 & 0 & +1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & +1 & -1 & -1 & 0 & 0 & 0 & 0 & \times & 0 & 0 & 0 \\ 0 & 0 & 0 & +1 & -1 & 0 & 0 & 0 & \times & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & +1 & -1 & +1 & 0 & \times & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & +1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} \Delta Q_1 \\ \Delta Q_2 \\ \Delta Q_3 \\ \Delta Q_4 \\ \Delta Q_5 \\ \Delta Q_6 \\ \Delta Q_7 \\ \hline \Delta H_c \\ \Delta H_d \\ \Delta H_e \\ \Delta H_f \\ \Delta H_g \end{bmatrix} =$$

$$\begin{bmatrix} -(-H_A + H_c + K_1 Q_1/Q_1) \\ -(-H_B + H_d + K_2 Q_2/Q_2) \\ -(-H_D + H_c + K_3 Q_3/Q_3) \\ -(-H_D + H_E + K_4 Q_4/Q_4) \\ -(-H_E + H_F + K_5 Q_5/Q_5) \end{bmatrix}$$

$$\begin{bmatrix} -(-H_F + H_g + K_6 Q_6/Q_6) \\ -(-H_c + H_e + K_7 Q_7/Q_7) \\ -(Q_1 + Q_3 - Q_7 - D_c) \\ -(Q_2 - Q_3 - Q_4 - D_d) \\ -(Q_4 - Q_5 - D_e) \\ -(Q_5 - Q_6 + Q_7 - D_f) \\ -(Q_6 - D_g) \end{bmatrix}$$

In each iteration, find deltas from:

$$\begin{bmatrix} \underline{\Delta Q} \\ \underline{\Delta H} \end{bmatrix} = \begin{bmatrix} n \underline{A}_{11} & \underline{A}_{12} \\ \underline{A}_{21} & \underline{0} \end{bmatrix}^{-1} \cdot \begin{bmatrix} -\underline{dE} \\ -\underline{dQ} \end{bmatrix}$$

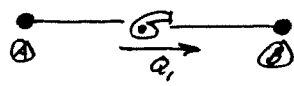
Then,

$$\begin{bmatrix} m+1 \underline{Q} \\ m+1 \underline{H} \end{bmatrix} = \begin{bmatrix} m \underline{Q} \\ m \underline{H} \end{bmatrix} + \begin{bmatrix} \underline{\Delta Q} \\ \underline{\Delta H} \end{bmatrix}$$

- Procedure:
- ① From network topology, form \underline{A}_{21} and \underline{A}_{12} matrices.
 - ② From pipe chars. and choice of head loss formula, form \underline{A}_{11} matrix.
 - ③ Guess initial values of all Q and H values (e.g. "1" for Q and some fgn value for H).
 - ④ Calculate $\begin{bmatrix} n \underline{A}_{11} & \underline{A}_{12} \\ \underline{A}_{21} & \underline{0} \end{bmatrix}^{-1}$ based on this iteration's Q values.
 - ⑤ Calculate $\begin{bmatrix} -\underline{dE} \\ -\underline{dQ} \end{bmatrix}$ based on this iteration's Q and H values.
 - ⑥ Calculate $\begin{bmatrix} \underline{\Delta Q} \\ \underline{\Delta H} \end{bmatrix}$ and then $\begin{bmatrix} m+1 \underline{Q} \\ m+1 \underline{H} \end{bmatrix}$.
 - ⑦ If $\begin{bmatrix} \underline{\Delta Q} \\ \underline{\Delta H} \end{bmatrix}$ satisfies convergence criterion, stop.
Else, iterate ④ \rightarrow ⑦.

→ Look at Excel file with coded example.

PUMPS IN GRADIENT METHOD

The pipe equation for  becomes:

$$H_A + (AQ_1^2 + BQ_1 + H_c) - H_B - K_1 \frac{Q_1}{|Q_1|^{n-1}} = 0$$

or

$$-H_A + H_B + K_1 \frac{Q_1}{|Q_1|^{n-1}} - (AQ_1^2 + BQ_1 + H_c) = 0 = F_{P1}$$

Which alters Newton method implementation:

$$\frac{\partial F_{P1}}{\partial Q_1} = n K_1 / |Q_1|^{n-1} - 2AQ_1 - B$$

and the element in the A_{ii} matrix will become

$$\begin{bmatrix} K_1 / |Q_1|^{n-1} + \frac{-2AQ_1 - B}{n} & 0 & \dots & \dots \\ 0 & K_2 / |Q_2|^{n-1} & 0 & \dots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}$$

since A_{ii} gets multiplied by n .